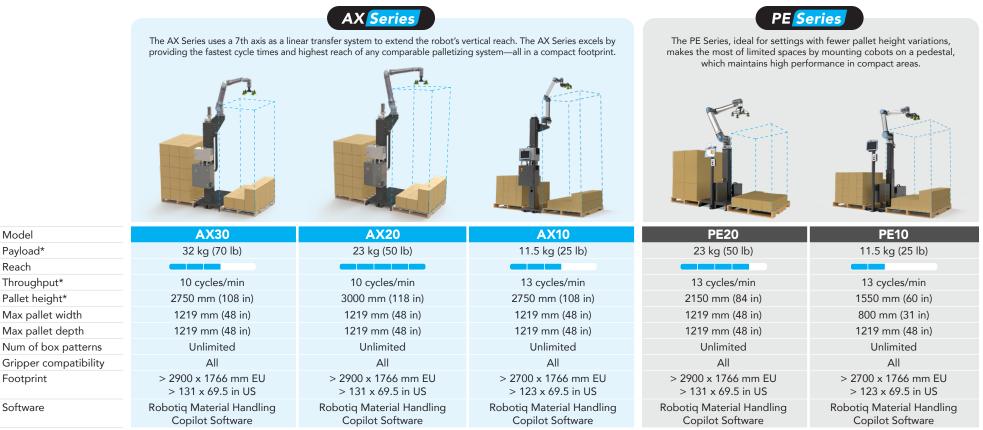
## TURNKEY PALLETIZING SOLUTION

A permanent fix for your staffing woes

<sup>II</sup> The ROI was a slam dunk. Smoothest equipment installation I have seen in 28 years. II

—Greg Thayer, VP, Cascade Coffee



Payload, throughput and pallet height depend on various factors. Quickly assess feasibility with the Robotig Online Configurator.

## Over 700 Robotig Palletizing Solutions have improved factory productivity worldwide.





Model

Reach

Payload\*

Software



Try the Palletizing Fit Tool to find the solution that fits your needs





1-888-Robotia robotig.com

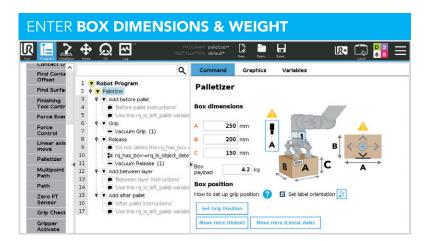
## SET UP YOUR APPLICATION IN 3 EASY STEPS

The Palletizing Solution is designed to make automation accessible, no matter your robotics knowledge level. All workers can operate and teach SKUs, risk-free.

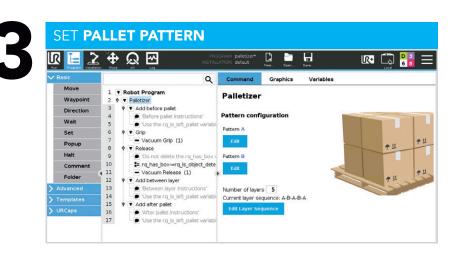
Create a pallet pattern to automatically generate and optimize all trajectories and robot movements. The software stores hundreds of recipes (SKUs/pallets) for easier and faster changeovers.

Launching our first palletizing program took me less than 45 minutes.

- Alliora employee



		ROGRAM palletzer* 🗋 📩 🖬 ALLATION default New. Open. See. Lead				
✓ Basic	م	Command Graphics Variables				
Move	1 V Robot Program					
Waypoint	2 Palletizer	Palletizer				
Direction	3 🕈 🔻 Add before pallet					
Wait	4 Before pallet instructions'	Pallet dimensions				
Set	5 ● 'Use the rq_is_left_pallet variab	SIDE				
	7 Vacuum Grip (1)	LEFT				
Popup	8 🕈 🔻 Release					
Halt	9 Do not delete the rq_has_box	Front 1000 mm				
Comment	10 = rq_has_box=rq_is_object_det	side 1200 mm				
Folder	4 11 - Vacuum Release (1)	RIGHT RIGHT				
Advanced	12        • Add between layer        13        • Between layer instructions'	Height 150 mm				
	14 Use the rg is left pallet variab					
> Templates	15 🕈 🕇 Add after pallet	Pallet selection				
> URCaps	16 After pallet instructions'	Pallet LEFT				
	17 • Use the rg_is_left_pallet variab					



✓ Basic		۹	Command	Graphics	Variables		
Move	1 .	Robot Program					
Waypoint		Palletizer	Palletizer				
Direction	3 9						
Wait	4 5	<ul> <li>Before pallet instructions'</li> <li>Use the rg is left pallet variab</li> </ul>	Pattern A editing				
Set	6 9	▼ Grip	<b>G</b>	1			
Popup	7 8 9	Vacuum Grip (1)	A stationers and	-			
Halt	9	<ul> <li>Release</li> <li>Do not delete the rg has box</li> </ul>		- ⊇ →			
Comment	10	= rq_has_box=rq_is_object_dete		1			
Folder	11 12 9	<ul> <li>Vacuum Release (1)</li> <li>Add between layer</li> </ul>	Delete box				
> Advanced	13	Between layer instructions'	Delete all				
> Templates	14	Use the rq_is_left_pallet variab		200			
> URCaps	15 P 16	Add after pallet     Add after pallet     Add after pallet instructions'	Movement step	200 r	m FRONT		